

Petri net and Rewriting Logic Based Formal Analysis of Multi-Agent Based Safety-Critical Systems

Ammar Boucherit^{a,*}, Laura M. Castro^b, Abdallah Khababa^c, Osman Hasan^d

^aComputer Science Department, University of El-Oued, Algeria

^bComputer Science Department, A Coruña University, Spain

^cComputer Science Department, University of Ferhat Abbas Sétif, Algeria

^dSchool of Electrical Engineering and Computer Science (SEECS), National University of Sciences and Technology (NUST), Pakistan

Abstract

The formal design and development of multi-agent systems has attracted a considerable attention over the past decades because of their extensive use in safety-critical applications. This paper presents an efficient, hybrid and scalable formal development approach for safety-critical systems based on the multi-agent paradigm. In fact, we aim in this paper to benefit from the advantages of existing tools and techniques for each development stage and then integrate them in one unified approach. In particular approach, we advocate using Petri nets and rewriting logic to facilitate the formalization of multi-agent based systems, as well as we have integrated both the model checking and property-based testing techniques in the verification and testing stages. For illustrating the utilization and effectiveness of the proposed approach, we use it to analyze a simple automated distributing machine.

Keywords: Multi-Agent System, Model-checking, Property-Based Testing, Petri net, Rewriting Logic.

1. Introduction

Over the past decades, the technological expansion in computer science and electronic domains have led to a variety of innovative software systems; later, so-called the revolution of electronic digital computer. Thereafter, software systems are become increasingly present in our environment for personal use, such as microwaves, mobile phones, washing machines, digital cameras, as well as collective such as military, medical and aeronautics. In fact, these systems have not only facilitated to make our daily activities more comfortable, but it is becoming so clear that our lives are shaped and increasingly controlled by software systems

*corresponding author

Email addresses: ammar-boucherit@univ-eloued.dz (Ammar Boucherit), lcastro@udc.es (Laura M. Castro), akhababa@univ-setif.dz (Abdallah Khababa), osman.hasan@seecs.nust.edu.pk (Osman Hasan)

till the extent that we cannot even imagine our world without them. However, such software systems are also responsible for an ever-increasing number of serious errors especially when it comes to safety-critical systems.

In this context, the use of multi-agent systems (MAS) has proven to be one of the most relevant approach to promote the development of real-time [1, 2] and complex systems [3, 4]. Nevertheless, due to the absence of available agent-specific safety analysis methods, it is so risky to use alone and trust agent-oriented methods in situations where safety is critical [5, 6]. Hence, the main interest in developing software for such systems is not just confined to clearly defining the system functions, interaction between components and properties of interest, but primordially on how one can identify and eliminate system errors in each development stage in order to ensure a successful implementation of the overall system.

To meet the high quality level and safety objectives satisfying the rising complexity of safety-critical systems, the use of adequate design approaches that support decentralized processing as well as rigorous analysis techniques and methods necessary to specify, design, implement and assess safety-related software systems, is gaining more and more importance.

Motivation

The present work is motivated by a desire to bridge the gap between formal specification, verification and testing during the design and development of multi-agent based critical systems. In this regard, the following issues must be addressed to increase the trustworthiness of safety-critical systems :

- i. The choice of the formalism for behavioral modeling of the safety-critical system.
- ii. The choice of a verification technique to ensure the correctness of the proposed model before proceeding to the system realization.
- iii. The choice of the code testing technique to ensure the absence of error before its implementation.

In this context, Multi-Agent Systems (MAS) represent an innovative paradigm for modeling, simulating and designing complex distributed systems [7, 8]. Their effectiveness is due to the ability of agents to represent the system entities, their behaviors and interactions. In fact, an agent has proactive and reactive features that are very useful in decision making. In addition, a key characteristic of MAS is the collective intelligence or distributed intelligence. In this context, it is well known in the domain of MAS that a single ant or bee (agent) is not smart, but their colonies (MAS) are characterized by numerous additional capabilities [9], such as solving complex tasks and finding the shortest path to the food source. Moreover, MAS can continue to function even with the failure of one of its components (agent), without degrading the system as a whole. This last feature is extremely important in the case of safety-critical systems. Therefore, the use of multi-agent systems is very advantageous for modeling safety-critical systems[10, 11, 12]. Nevertheless, given the lack of a formal, standardized method for the development of agent-based systems, software engineering for agent-based critical systems is quite challenging.

Then, Petri nets [13] represent a well-defined theoretical model of concurrency in which the temporal ordering and causal relationships between system actions can be easily represented.

Therefore, Petri nets are widely accepted for modeling and analyzing complex, dynamic and concurrent systems, like command and control systems [14], industrial real-time applications [15] and safety-critical systems [16, 17]. In addition and in the context of MAS, Petri nets are one of the most reliable formalisms for simulation and analysis of both behavioral modeling and failure analysis of MAS [18]. One of the distinguishing features of Petri nets is that they provide a graphical representation of the dynamic behavior of systems by enabling visualization of the state changes in the modeled system that greatly facilitates the analysis process [19]. These features of Petri nets are the key reason behind their wide popularity in the context of MAS [20, 21]. However, this potential of Petri nets should not deter the inherited difficulties and the increasing need for formal methods [22] and tools facilitating the analysis of large scale Petri net models.

For this purpose, we advocate the use of Maude [23] on the specification stage as a formal specification language based on rewriting logic [24] for describing Petri nets based MAS models. However, the existing rewriting logic based framework for petri nets [25] needs some enhancements, namely, additional operators to facilitate counting or testing the number of tokens in a Petri net place. In addition, Petri nets require automatic tools to facilitate the transcription of their models into Maude specifications. Such operation is usually time consuming and error-prone in the case of large scale and complex models when performed manually. In order to overcome these limitations, we propose to benefit from this work [26], which presents an efficient algorithm allowing the automatic generation of Maude specifications for multi-agent system models based on Petri nets. Moreover, the choice of using Maude is also motivated by the availability of an integrated tool set that facilitates the formal verification of Petri net models, such as Maude model-checker [27], the reachability analysis tool and Maude’s inductive theorem prover (ITP) [28].

Similarly, we advocate the use of property-based testing (PBT) [29], which is an automatic verification technique of the proposed code skeletons based on random generation of test sequences (i.e. test scenarios). Contrary to the classic testing, the PBT technique is used to automatically test code skeletons or algorithms before implementation.

The main objective of this work is on the formal analysis of MAS based safety-critical systems by the proposition of a new approach that covers almost all the development stages. To the best of our knowledge, both the enhanced Petri net specification and the combination of model checking with PBT techniques has never been used in similar context before.

The remainder of this paper is structured as follows: Section 2 discusses some related works. Then, Section 3 presents a literature review about MAS formalization. In Section 4, we briefly present our proposed approach for the formal analysis of multi-agent based safety-critical systems followed by a simple case study to show its feasibility in Section 5. Finally, Section 6 concludes the paper and presents some perspectives for future work.

2. Related works

We mean by safety-critical systems all systems in which failures may lead to catastrophic consequences, such as loss of human life, significant damage to the environment, and/or financial disasters. In such a case, multi-agent systems have been widely used to better

developing [30, 31], simulating [32], securing [33] and analyzing [34] of critical systems. Firstly, in [10], the main objective was to propose a formal methodology in order to ensure the correctness properties of safety and liveness of the Mail Transport System. While specifying Gaia based multi-agent requirement and design specifications, authors used regular expression in specifying the liveness properties and the first-order predicate calculus to specify the safety property. In the verification stage, The Finite State Processes (FSP) and Labelled Transition System (LTS) are used. Then, Event-B is exploited for creating exhaustive proofs.

Secondly, a multi-agent approach is proposed in [12] to ensure the reliability problem of an Air Traffic Control (ATC). Therefore, an agent-based decision-aided system was developed to help controllers in using their multiple software tools in critical situations such as the unavailability of some tools due to technical incidents. Practically, a simulation environment is used to test the MAS and demonstrate its significance to air traffic controllers.

Thirdly, a simulation-based hazard analysis method using multi-agent modeling has been presented in [35] to explore the effects of deviant node behaviour within a System of System (SoS). In comparison with traditional hazard analysis techniques, the presented method in this paper has demonstrated its powerfulness to reveal hidden and undiscovered hazards.

In addition, a formal development of a hospital MAS by refinement in Event-B has been presented in [36]. In this work, authors focused on modelling and verification of some safety critical activities such as consistent updates of patient data and handling emergencies. The main properties of MAS have been formalized and demonstrated using Event-B. However, due to the autonomous agent behaviour, the highly dynamic nature of a hospital and volatile error-prone communication environment, ensuring correctness of these activities was not a trivial task.

Moreover, in [37], agent-based modeling has been investigated to study and simulate the interdependencies in critical infrastructures. In fact, authors had proposed to adopt UML for better representing the interdependencies between the different components of the critical system. Thereafter, it has been exploited to simulate such complex systems through multi-agent paradigm.

Analyzing the characteristics of the presented works, it is possible to conclude that a promising approach for developing multi-agent based safety-critical system will be very advantageous if it based on Petri nets as a well-defined theoretical model of concurrency on the modeling stage. Then, the use of rewriting logic at the specification stage will provide many benefits for both specification and verification purposes because of the Maude associated formal analysis tools. Finally, the integration of a powerful technique to ensure the absence of code error during the system implementation will raise the use of such approach in critical system context.

3. Multi-Agent Based Systems Formalization : Literature Review

Formalization is a process that starts with the construction of a formal model (a precise description of the system structure, services and relationships) of the targeted system. Its purpose is to assist designers in proving the conformity of the system with its specification.

In this context, a large number of approaches, programming languages and graphical (or textual) formalisms have been used to describe all aspects of multi-agent systems such as CASL [38], SLABS [39], XABSL [40] and others [41, 42]. Nevertheless, it would be difficult to present an exhaustive list of all these works, and we therefore recall only a few works that we consider very important from the point of view of their relevance and their widespread usage.

3.1. Specification Approaches

On the basis of specification formalisms and languages, one can easily find that Petri nets are still considered as one of the most used formalisms to help designers formalize and simulate MAS models [21, 43]. For instances, Petri nets and derivatives have been widely used to describe the social and behavioral aspects of agents [44, 45], interaction protocols [46] as well as cooperation and coordination in multi-agent systems [47]. Indeed, Petri nets have also been favored for the analysis of multi-agent systems because of the exact mathematical definition of their semantics of execution as well as the theory developed around them. The corresponding Petri net models of the multi-agent based systems are evaluated using the existing analysis methodologies and simulation techniques for Petri nets [48, 49]. Similarly, Maude has been used in several works for the formal specification of multi-agent systems [50, 51]. In addition, Maude was used to implement a (simplified language of) cognitive agent programming language 3APL in [52]. This work has been enhanced for prototyping the BUPL agent programming language (Belief Update programming language) and for executing agent programs [53]. Moreover, Maude is used in [54, 55] to formalize their agent based models, which are then simulated and verified using associated tools. However, the main disadvantage of all these works is that the translation of the models of the multi-agent systems to a Maude specification is done manually and in an ad hoc manner. It can therefore be quite difficult to ensure that this specification is a true description of the models of multi-agent systems studied especially in the case of complex models.

In this context, UML [56, 57] is widely used to describe the different aspects of multi-agent systems. In addition, the UML language has been a subject of several extensions to capture other aspects of multi-agent systems. For example, AML [58], MAS-ML [59] and AUML [60]. Moreover, many other works have emerged to develop a special Object Constraint Language (OCL) [61, 62] allowing to reduce the ambiguity and the misunderstanding of the models by specifying additional constraints on the behavior of the components of the studied system.

Similarly, architecture description languages (ADLs) are a particular type of languages that provide a concrete syntax for specifying system architectures in a more abstract, flexible and robust way than other traditional approaches. They have been widely used for the description of architectures of multi-agent systems [63, 64].

Except some works that propose a formal UML (or ADL) based description for MAS [65, 66], the major problem with most ADLs and UML is that they lack formal semantics, explicit support for running a description of the architecture, and ensuring compliance between a system and a user-specified architecture. For instance, some works were focused on the translation or combination of UML [67, 68] and ADLs [69, 70] into Petri nets to benefit

from the existing formal analysis tools. Other authors attempted to translate UML diagrams [71, 72] and software architecture description language models [73, 74] into rewriting logic. Moreover, some authors proposed rewriting logic (resp, Petri net) based ADLs [75, 76] (resp, [77, 78]) in order to obtain a formal description and simulation mechanism for the studied system architecture.

3.2. Verification Approaches

The verification of multi-agent systems is gaining more importance [79, 80]. For instance, a considerable amount of work has been done to verify the behavior of agents [81, 82], analyzing interaction protocols and their communication languages [83, 84] as well as to simulate and control security in multi-agent systems [85, 86]. However, we can see that the existing research works are generally directed towards the creation of verification tools for multi-agent systems, otherwise, they are based on existing model checkers. Table 1 presents a summary of the most known model-checkers based works, alongside the used formalism for system and/or property specification.

Work	System Specification	Property Specification	Verification Tool	Year
Wooldridge et al. [87]	MABLE	LORA	SPIN	2002
Benerecetti et al. [88]	Binary Decision Diagrams	MATL	NuMAS	2002
Bordini et al. [89, 90]	AgentSpeak(F)	LTL	SPIN	2003
Gammie et al. [91]	Binary Decision Diagrams	CTL / LTL	MCK	2004
Lomuscio et al. [92]	Interpreted Systems Programming Language (ISPL)	Alternating-time Temporal Logic (ATL)	MCMAS	2006
Belala et al. [93]	Multi-Formalisms	LTL	Maude Model-Checker	2006
Riemsdijk et al. [52]	3APL	LTL	Maude Model-Checker	2006
Lomuscio et al. [94]	Interpreted Systems	CTLK	NuSMV	2007
Rodion et al. [95]	Alloy	Alloy's relational algebra	Alloy Analyzer	2007
Boudiaf et al. [55]	Rewriting Theories	LTL	Maude Model-Checker	2008
Nabialek et al. [96]	Multi-Formalisms	CTLKD	VerICS	2008
Astefanoaei et al. [97]	Normative MAS Language	LTL	Maude Model-Checker	2009
D'Souza et al. [98]	State Chart Diagrams	CTL	NuSMV2	2012
Laouadi et al. [54]	Agent UML	LTL	Maude Model-Checker	2017
Jeremy et al. [99]	Interpreted Systems	CTLK	MCMAS	2017

Table 1: Summary of works using model-checkers for MAS verification

3.3. Synthesis

The specification of a multi-agent system involves the identification of a large number of entities and their relationships. For this, several types of formalisms have been used to construct the most appropriate system model to verify the properties in question and not to be limited — if necessary — on the use of a single formalism so to manage the different perspectives of the system [100].

In this context, we can easily deduce that Petri nets and rewriting logic are quite well-suited for MAS modeling and specification. At the verification stage, Maude is widely used as a formal semantic framework in many works for the verification of multi-agent systems and therefore its use is very appropriate and endorsed.

In addition, within the scope of enhancing multi-agent based systems quality, numerous other testing based works have been realized [101, 102]. However, it is better if testing strategies are combined (used jointly) with model checking based ones in order to better guarantee the system implementation quality.

Based on the literature review about MAS formalization, the fundamental steps of a formal analysis approach of multi-agent based systems can be summarized in the following three points:

- i. Clearly define the structure and behavior of the system using the appropriate modeling formalisms and/or the most adapted formal specification languages.
- ii. Identify the risks and errors of the system — which may be catastrophic or expensive — to support and better verify its corresponding properties using formal verification techniques.
- iii. Ensure that the system implementation meets the specification and that the proposed code will not make errors using advanced testing techniques.

4. Proposed Formal Analysis Approach of Multi-Agent Based Safety-Critical Systems

The proposed approach for the formal development and analysis of behavioral aspect of multi-agent based safety-critical systems contemplates the following phases of software development: modeling, specification, validation, and testing. The next subsections provide an overview of each stage of the proposed approach.

4.1. Modeling Stage

The goal of this first stage is to construct the Petri net model formalizing the dynamic behavior of the studied system. In addition, the designer uses rewriting logic, which is a very expressive logic to give formal semantics when specifying Petri net models. Depending on the system studied, a system may have several operational phases, generally: startup, initialization, processing etc. Usually, each operational phase may have its own model. Therefore, it is necessary in the case of some complex systems to built more than one model, and according to the property or aspect to be verified, the designer must prepare an independent (separate) Petri net model before the complete model is developed.

4.2. Specification Stage

This stage is intended to prepare two specification levels :

- 1) System Specification: The main objective of the specification level is to translate the proposed model into rewriting logic by using an enhanced proposed specification for Petri nets based on rewriting logic.
- 2) Properties Specification: If the aim of system specification level, is to give a more or less abstract description of the system then the system can be formally defined by its properties. In this step, we refer to the created model and its specification to prepare a module that defines the set of predicates expressed in standard LTL propositional logic. These predicates are considered by the Maude's model-checker tool as the set of verified properties in the system. Then, the set of properties to be checked must be expressed in LTL as well.

4.3. Verification Stage

The verification stage is used to show that the system satisfies the desired properties and that it exhibits a stable behavior, and/or certifies that the probable malfunctions of the system will not causes damages.

The following two verification tools may be used in this stage:

- *LTL Model-Checker* : It checks the properties of a model by expressing them in linear temporal logic (LTL).
- *Search Tool* : This tool may overcome some of the shortcomings of the model-checking technique. For instance, it allows designers to check the absence/existence of some worst-cases — offered by experts in the field — that may not be expressible in LTL. In addition, it presents all the possible scenarios for the such worst-cases if they exist, which is not the case for the model-checker counter example (single scenario).

4.4. Testing Phase

The more complex a software system is, the more difficult (or unfeasible) its formal verification becomes. In addition, even if the model has been completely verified by model checking techniques, its full realization also needs to be tested. In the final stage of our approach, we advocate to use property-based testing to test the proposed implementation of the SUT. Therefore, we define all desired properties in addition to those that have not been verified in earlier phases as universally quantified expressions, and devote as much time as available to automatically generate, run, and evaluate them as test cases. In this step, we propose to use QuickCheck's capabilities to produce shunk (i.e. simplified) counterexamples when a specific test case is found to show how that the realization of the system violates a given property.

5. Case Study

5.1. System Description and Modeling

To show the practical usefulness and effectiveness of the proposed approach, we consider a simple automated distributing machine placed in a hotel to provide coffee, cakes and beverage items to hotel visitors. The visitor has to use his magnetic hotel visitor card to gain services from the machine.

Such a machine is daily programmed to deliver a cup of coffee, cake with a bottle of water and juice (**Service 1**) to the visitor upon the first usage of his card. Otherwise, the machine delivers only coffee and cake (**Service 2**). For that, the machine tests the inserted card to check its validity and determines if it is the first use for a card or no. Thereafter, the corresponding service is delivered.

For the sake of simplicity, we assume that the visitor card contains a bar code with 14 digits where the addition of digits in positions (1, 2, 4, 8) equals to 20. In addition, the card codes of the present visitors in the hotels are inserted daily in a list into the memory of the machine and when a valid visitor card is used, it will be automatically deleted from this list. Such a mechanism facilitates the process to deliver **Service 1** or **Service 2** to a visitor. Therefore, in both cases (**Testing card validity** and **Determining services**), two algorithms are used for verification. Figure. 1 shows the Petri net that models the described machine, and Table 2 presents the meaning of places and transitions.

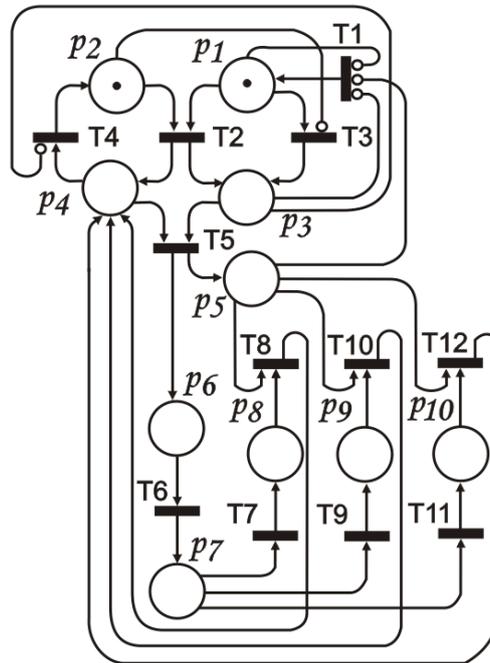


Figure 1: Petri Net model of the automatic distributor

Place labels with meaning	
P1	A visitor is coming and waiting for the machine to start up
P2	Machine in the state Idle (sleep)
P3	A visitor is ready (to insert his card)
P4	Machine is ready for use
P5	A visitor is using the machine (waiting test and/or services)
P6	Card is inserted
P7	Card is tested
P8	Invalid card is rejected
P9	Delivering service 1 and rejecting card
P10	Delivering service 2 and rejecting card

Transition labels with meaning	
T1	Add new visitor to use the machine (only if there is no one waiting, ready or using the machine)
T2	A visitor pushes the start button of the machine
T3	Changing visitor state to ready (if the machine is not in the sleep state)
T4	The machine returns to the Idle state (if there is no visitor in ready state)
T5	Inserting card
T6	Testing card
T7	Rejecting invalid card
T8	Visitor takes invalid card and goes away
T9	Accepting card and delivering service 1
T10	Visitor takes his card with service 1 and goes away
T11	Accepting card and delivering service 2
T12	Visitor takes his card with service 2 and goes away

Table 2: Meaning of Petri net places and transitions

5.2. System and Properties Specification

We should note that the existing rewriting logic semantics for Petri nets does not support (without other additional operators) neither the specification of inhibitor arcs nor counting the number of tokens in a specific place. Therefore, we propose an enhanced specification that alleviates such two limitations.

5.2.1. System Specification

The corresponding rewrite theory of the Petri net model is illustrated in the following modules :

```

fmod PETRI_NET is
protecting INT .
sorts PlaceName Places Marking .
subsort Places < Marking .
ops P1 P2 P3 P4 P5 P6 P7 P8 P9 P10 : -> PlaceName .
op place(,_) : PlaceName Int -> Places [ctor] .
op __ : Marking Marking -> Marking [ctor assoc comm id:null] .
op null : -> Marking .
endfm
mod PN_ADM is
protecting PETRI_NET .
rl[T1]: place(P1,0) place(P3,0) place(P5,0) => place(P1,1) place(P3,0) place(P5,0) .
rl[T2]: place(P1,1) place(P2,1) place(P3,0) place(P4,0) => place(P1,0) place(P2,0)
place(P3,1) place(P4,1) .
rl[T3]: place(P1,1) place(P2,0) place(P3,0) => place(P1,0) place(P2,0) place(P3,1) .
rl[T4]: place(P2,0) place(P3,0) place(P4,1) => place(P2,1) place(P3,0) place(P4,0) .
rl[T5]: place(P3,1) place(P4,1) place(P5,0) place(P6,0) => place(P3,0) place(P4,0)
place(P5,1) place(P6,1) .
rl[T6]: place(P6,1) place(P7,0) => place(P6,0) place(P7,1) .
rl[T7]: place(P7,1) place(P8,0) => place(P7,0) place(P8,1) .
rl[T8]: place(P8,1) place(P4,0) place(P5,1) => place(P8,0) place(P4,1) place(P5,0) .
rl[T9]: place(P7,1) place(P9,0) => place(P7,0) place(P9,1) .
rl[T10]: place(P9,1) place(P4,0) place(P5,1) => place(P9,0) place(P4,1) place(P5,0) .
rl[T11]: place(P7,1) place(P10,0) => place(P7,0) place(P10,1) .
rl[T12]: place(P10,1) place(P4,0) place(P5,1) => place(P10,0) place(P4,1) place(P5,0) .
endm

```

In this specification, the static aspect (the signature) of the system is defined in the functional module `PETRI_NET`. This module has been imported in the system module `PN_ADM`, in which we add a rule for each transition to complete describing the dynamic aspect of the machine.

5.2.2. Properties Specification

In the case of our system, the following properties have to be verified :

- *System evolution*: This property ensures that the system is always (or able to be) active and it will not be blocked in a deadlock situation.
- *Serving visitors*: This property ensures that whenever a visitor is present and wants to take something from the machine, he must be served, either by Service 1, Service 2 or his card is rejected if it is not valid.
- *Determining services*: This property ensures that each visitor gets Service 1 at the first time and Service 2 after that. In fact, this property is very important for the hotel due to the financial loss it can incur. Therefore, it must be rigorously verified.

Then, two modules for the specification of system properties are prepared. The first module, `PN_ADM_PREDS`, describes of the set of properties that are assumed to be verified in the model and that will be used as a reference in the process of verification by the model checking tool. However, in the second module, `ACS-CHECK`, the designer expresses the relevant properties to be checked in the system model. This module contains the properties that are expressible in LTL only. These modules are given as follows:

```

mod PN_ADM_PREDS is
protecting PN_ADM .
including SATISFACTION .
subsort Marking < State .
ops New-V-Coming V-Ready V-Use-Machine : -> Prop .
ops Machine-Sleep Machine-Ready Machine-In-Use : -> Prop .
ops Reject-Card Service-1 Service-2 : -> Prop .
var A : Marking .
*** ----- SOME IMPORTANT PROPERTIES -----
eq place(P1,1) A |= New-V-Coming = true .
eq place(P3,1) A |= V-Ready = true .
eq place(P5,1) A |= V-Use-Machine = true .
eq place(P2,1) A |= Machine-Sleep = true .
eq place(P4,1) A |= Machine-Ready = true .
eq place(P6,1) A |= Machine-In-Use = true .
eq place(P7,1) A |= Machine-In-Use = true .
eq place(P7,1) place(P5,1) A |= Reject-Card = true .
eq place(P7,1) place(P5,1) A |= Service-1 = true .
eq place(P7,1) place(P5,1) A |= Service-2 = true .
endm

mod ADM-CHECK is
inc PN_ADM_PREDS .
inc MODEL-CHECKER .
inc LTL-SIMPLIFIER .
op initial : -> Marking .
eq initial = place(P1,1) place(P2,1) place(P3,0) place(P4,0) place(P5,0) place(P6,0)
              place(P7,0) place(P8,0) .
ops no-deadlock serving : -> Prop .
eq no-deadlock = [] (New-V-Coming \\/ V-Ready \\/ V-Use-Machine \\/ Machine-Ready \\/
                    Machine-Sleep \\/ Reject-Card \\/ Service-1 \\/ Service-2 ) .
eq serving = [] ((P-Use-Machine) -> <> (Reject-Card \\/ Service-1 \\/ Service-2)) .
endm

```

5.3. Verification

Starting from the initial state of the Petri net, the Maude LTL model-checker has been used for the verification of two properties.

- *System evolution*: This property is defined in the module ADM-CHECK as "no-deadlock". After verification, the LTL model-checker confirmed the correctness of this property as follows:

```

Maude> reduce in ADM_CHECK : modelCheck(initial, no-deadlock) .
rewrites: 653 in -42042743134ms cpu (31ms real) (~ rewrites/second)
result Bool: true

```

- *Serving visitors*: This property is defined as "serving" in the module ADM-CHECK. The LTL model-checker also confirmed the correctness of this property.

```

Maude> reduce in ADM_CHECK : modelCheck(initial, serving) .
rewrites: 70 in -41991903084ms cpu (0ms real) (~ rewrites/second)
result Bool: true

```

5.4. Testing

As per the proposed approach, we used PBT to test the “*Determining service*” property mentioned in Section 5.2.2. In fact, this property is not expressible as a LTL formula and cannot be verified even by the Maude “*search tool*” since it is related to the implementation and not to the system model. However, it can be translated into a number of declarative properties, such as:

```

property_first_time_client_gets_first_service() ->
  ?FORALL(Client, valid_client_card(),
    proper_first_service(sut:use_machine(Client))).

property_following_times_client_gets_second_service() ->
  ?FORALL({Client, Uses}, {valid_client_card(), nat()},
    proper_second_service(
      repeat(Uses+1, sut, use_machine, [Client]))).

```

These two functions aim to test the two possibilities when it comes to the service control: either the client should get the first service when using the machine, or else the card had already been used and so the service should be the second type. These statements should hold *for all* the *valid client cards* that we test.

In this first formulation, the kind of testing to be performed is *positive testing*, since only *valid* client cards are generated to be used as input. The `valid_client_card` function is a data generator that, to comply with the description in Section 5.1, could be implemented as follows:

```

valid_client_card() ->
  ?SUCHTHAT({P1,P2,P3,P4,P5,P6,P7,P8,P9,P10,P11,P12,P13,P14},
    {nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),nat(),
     nat(),nat()}, P1+P2+P4+P8 == 20).

```

where `nat()` is a QuickCheck data generator that produces random natural numbers. Our customized generator produces sequences of 14 natural numbers, but only returns those that fulfill the condition $P1+P2+P4+P8 == 20$.

The additional helper functions `proper_first_service` and `proper_second_service` are used to check the result of invoking the functionality under test on the SUT (`sut:use_machine(Client)`). We include them here to illustrate how using the Erlang version of QuickCheck allows us to implement these kinds of test codes, regardless of the actual technology used to implement the SUT. In fact, the properties needed to be defined in a declarative manner, using the typical artefacts of a functional language (such as pattern-matching, heavily exploited here), like Erlang :

```

proper_first_service(coffee) -> true;
proper_first_service(cake) -> true;
proper_first_service(water) -> true;
proper_first_service(juice) -> true;
proper_first_service(_) -> false.

proper_second_service(coffee) -> true;
proper_second_service(cake) -> true;
proper_second_service(_) -> false.

```

Finally, we take advantage of recursion to implement one last helper to invoke the SUT a random number of times, to simulate the card being used n times after the first time. Again, *for all* ns that we generate, the above property should hold.

```

repeat(1, Mod, Op, Args) ->
  erlang:apply(Mod, Op, Args);
repeat(N, Mod, Op, Args) ->
  erlang:apply(Mod, Op, Args),
  repeat(N-1, Mod, Op, Args).

```


If the SUT had a similar functionality to that of `valid_client_card` then it should be tested against this helper function in a property that states that *for all* client cards, both the helper function and the SUT implementation should generate the same output for a given card.

Last but not least, we could also test the behaviour of the SUT when a card is invalid. In doing so, we would generate invalid card data on purpose, and test that invoking the SUT always returns the no service message. This property can be expressed as follows:

```

property_invalid_client_gets_no_service() ->
  ?FORALL({Client, Uses}, {invalid_client_card(), nat()},
  begin
    FirstOutput = sut:use_machine(Client),
    FollowingOutput = repeat(Uses+1, sut, use_machine, Client]),
    not proper_first_service(Output)
    andalso not proper_second_service(Output)
  end).

```

5.5. Discussion and Motivation

Based on the above-mentioned analysis, we now highlight the main advantages of the proposed approach. In the modeling stage, we justify the selection of the Petri net among many other formalisms, such as UML diagrams, and architecture description languages (ADL) based on the following points:

- **Expressiveness:** In addition to the intuitive graphical representation, the expressiveness of Petri nets, makes it a very suitable formalism for modeling and analyzing a rich variety of systems and applications including, concurrent, distributed and critical system architectures.
- **Formal Semantics:** Since Petri Net is one of the most important formalisms having a well-defined formal semantic and theoretical foundation, it is widely used to formalize not only systems but even other modeling techniques and description languages that are used to describe software architecture (see, Sec. 3.1).
- **Formal analysis:** Petri net has gained wide acceptance as a modeling technique in both industrial and academic areas because of the existence of a large number of analysis tools [103, 104] and techniques [105] for Petri net based models.

The specification language used in our approach is Maude. This choice is motivated by the expressiveness, modularity and parametrization of Maude. Moreover, the rewriting logic allows us to naturally express both flat and hierarchically composite Petri net models. Finally, the availability of a large number of integrated tools, such as Maude model-checker [27] and Maude search tool, facilitate the formal verification of Petri net models in the verification stage. These tools cannot be used to analyze infinite-state systems, and for such systems Maude supports reachability analysis and model checking, including model checking for a useful class of temporal logic formulas. Furthermore, due to the reflective nature of its logic and its implementation, such a library can be easily extended by the user with new

model checking strategies.

Because of the excellent results obtained in the context of MAS [101], we advocate the use of property-based testing (PBT) for the testing stage. Indeed, testing is the last checkpoint at which software errors can be detected before a system goes into operation. However, it leaves all responsibility of designing and writing test scenarios to a human developer, who is limited by time constraints and usually based on his/her own experience and views on the SUT [106]. PBT has proven to play a vital role — as an automatic technique — in detecting corner cases that usually slip through human-conducted testing [107]. Moreover, PBT supports randomness for the generation of test sequences (i.e. test scenarios) themselves not only to alleviate the human factor, but also to compromise effort and correctness [108].

Consequently, we can say that we have proposed a generic approach that covers all software development stages. Thus, we have used rewriting logic as a unifying semantic framework in the specification stage, Maude model checking tool to check model properties, and finally QuickCheck’s property-based testing at the implementation level, to raise the confidence on the realization of the given system.

6. Conclusion and Future Work

In this paper, we have presented a new user-friendly approach for the formal analysis of behavioral software architecture of multi-agent based safety-critical systems. The proposed approach has been tested on a case study and results have been found to be quite promising. The ultimate objectives of our approach were :

- i. Using the Petri net formalism in the modeling stage to prepare an appropriate model of the given system architecture. Then, the rewriting logic is used for the specification of petri net in an enhanced version that naturally allows the specification of inhibitor arcs and count tokens in a Petri net place.
- ii. Combining model-checking and PBT techniques to ensure the absence of any error or unexpected behavior in the specification and implementation of the software under design.

In the future, we plan to develop and implement an algorithm for the automatic generation of rewriting logic specification of Petri nets; according to the enhanced semantics. Such algorithm will enlarge and facilitate the use of our approach and permit developers to benefit from the Maude associated formal analysis tools while developing their safety-critical systems.

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Author's bio



Ammar Boucherit is an associate professor at the University of El-Oued, Algeria. He holds his PhD degree in Computer Science from University of Ferhat Abbas, Sétif, Algeria. His research focused on three areas: formal design of computer systems, software architecture and multi-agents systems.



Laura M. Castro is an associate professor at the University of A Coruña, Spain. She is a member of the MADS (Models and Applications of Distributed Systems) research group. She gives lectures on Software Architecture, Software Verification and Validation. Her research focuses on software testing (automated, model and property-based testing), applied to software in general, and distributed, concurrent, functional systems in particular.



Abdallah Khababa is currently a full professor at the University of Ferhat abbas Sétif, Algeria. He holds a Ph.D. in computer science from the University of Ferhat Abbas Sétif. His main areas of interest include cognitive science and artificial intelligence, knowledge representation with ontologies and human-machine interface and its usability.



Osman Hasan is the senior head of department of electrical engineering SEECS and the director of the system analysis and verification (SAVe) Lab at NUST SEECS. His main research interests include formal verification, interactive theorem proving and higher-order logic. Prior to joining NUST SEECS, He did his PhD and post-doctoral fellowship from the hardware verification group at Concordia University, Montreal Canada.